



NOTES:-

1. With a positive current applied to pin "H" with respect pin "I", rotation shall be clockwise, facing mounting end of motor.
(with this rotation, a positive voltage shall be generated on pin "A" with respect to pin "B" of tach)
2. Motor may be mounted in any position.
3. All dimensions in inches with metric equivalent in ()

Model No.	"A" Max
TT 2950-1011	8.25 (210)
TT 2952-1011	9.70 (246)
TT 2953-1011	12.60 (320)
TT 2954-1011	14.05 (357)

				Tolerances: XXX = ± 0.015" XXXX = ± 0.005" Ang. Dim. = ± 1°		Surface: 6.3 		Scale: Weight:	
				Drawn: 29/3/05 Date:		Name: POB		Material: Remove all burrs and sharp corners.	
				App'd:		Norm:		DC SERVOMOTOR TT 295X-1011	
				Issue: 1		C.N.C.O. No.:		Date:	
				Name:		App'd:		TT 295x-1011	
				Rep'd By:		Date:		Sheet: 1 Of: 1	
				bobby servo-electronic ag		Rep'd By:		Date:	